

Formulari de Relativitat General

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I. GEOMETRIA DIFERENCIAL

Camps de vectors i corbes integrals

$$\vec{v} \equiv \frac{d}{d\lambda} = \frac{dx^i}{d\lambda} \Big|_p \frac{\partial}{\partial x^i} = v^i(x) \partial_i \rightarrow v^i(x) = \frac{dx^i}{d\lambda}$$

Commutador: $[\vec{v}, \vec{w}] = (v^i \partial_i w^j - w^i \partial_i v^j) \partial_j = -[\vec{w}, \vec{v}]$
 $\{\vec{v}_i\}$ és base coordenada $\Leftrightarrow [\vec{v}_{(j)}, \vec{v}_{(k)}] = 0$.

Tensors en una varietat

Vectors i vectors duals:

$$\vec{v} = v^i \vec{e}_i = v^i \partial_i \in T_p \quad \tilde{p} = p_i \tilde{\omega}^i = p_i \tilde{d}x^i \in T_p^*$$

$$\tilde{\omega}^j(\vec{e}_i) = \tilde{d}x^j(\partial_i) = \frac{\partial x^j}{\partial x^i} = \delta_j^i \quad \tilde{d}f = \frac{\partial f}{\partial x^i} \tilde{d}x^i$$

$$\vec{e}_{i'} = \Lambda_{i'}^i \vec{e}_i \quad \tilde{\omega}^{i'} = \Lambda_i^{i'} \tilde{\omega}^i \quad v^{i'} = \Lambda_i^{i'} v^i \quad p_{i'} = \Lambda_{i'}^i p_i$$

Tensor $\binom{N}{M}$: $\mathbf{T} : T_p^* \times \dots \times T_p^* \times T_p \times \dots \times T_p \rightarrow \mathbb{R}$

$$\mathbf{T} = T_{k\dots l}^{i\dots j} (\vec{e}_i \otimes \dots \otimes \vec{e}_j \otimes \tilde{\omega}_k \otimes \dots \otimes \tilde{\omega}_l)$$

$$T_{k'\dots l'}^{i'\dots j'} = \Lambda_i^{i'} \dots \Lambda_j^{j'} \Lambda_{k'}^k \dots \Lambda_{l'}^l T_{k\dots l}^{i\dots j}$$

Mètrica: \mathbf{g} , tensor $\binom{0}{2}$:

$$\mathbf{g} = g_{ij} \tilde{\omega}^i \otimes \tilde{\omega}^j = \mathbf{g}(\vec{e}_i, \vec{e}_j) (\tilde{\omega}^i \otimes \tilde{\omega}^j) \equiv \vec{e}_i \cdot \vec{e}_j (\tilde{\omega}^i \otimes \tilde{\omega}^j)$$

$$g_{ij} g^{ik} = \delta_j^k \quad v_i = g_{ij} v^j \quad v^i = g^{ij} v_j \quad \vec{v} \cdot \vec{w} = g_{ij} v^i w^j = v_j w^j$$

Derivada de Lie

$$\mathcal{L}_{\vec{v}} f|_{t_0} = v^i \frac{\partial f}{\partial x^i} = \vec{v}(f) \quad \mathcal{L}_{\vec{u}} \vec{v} = [\vec{u}, \vec{v}]$$

Transport d'un vector per Lie:

$$\mathcal{L}_{\vec{u}} \vec{v} = 0 \rightarrow u^i \partial_i v^j - v^i \partial_i u^j = 0$$

Propietats:

$$\mathcal{L}_{\vec{v}}(\vec{p}(\vec{u})) = (\mathcal{L}_{\vec{v}} \vec{p})(\vec{u}) + \vec{p}(\mathcal{L}_{\vec{v}} \vec{u})$$

$$\mathcal{L}_{\vec{v}}(\mathbf{T} \otimes \mathbf{Q}) = (\mathcal{L}_{\vec{v}} \mathbf{T}) \otimes \mathbf{Q} + \mathbf{T} \otimes (\mathcal{L}_{\vec{v}} \mathbf{Q})$$

$$\mathcal{L}_{\vec{v}}(\tilde{d}f) = \tilde{d} \mathcal{L}_{\vec{v}}(f) \quad \mathcal{L}_{a\vec{v}} = a \mathcal{L}_{\vec{v}} \quad \mathcal{L}_{[\vec{v}, \vec{u}]} = [\mathcal{L}_{\vec{v}}, \mathcal{L}_{\vec{u}}]$$

Simetries i vectors de Killing

Equació de Killing:

$$\mathcal{L}_{\vec{v}} \mathbf{g} = 0$$

$$(\mathcal{L}_{\vec{v}} \mathbf{g})_{ij} = v^k \partial_k g_{ij} + \partial_i v^k g_{kj} + \partial_j v^k g_{ik}$$

Nombre màxim: $\frac{n(n+1)}{2} \quad \partial_j v_i + \partial_i v_j = 2v_l \Gamma_{ji}^l$

p-formes

Components, dimensió i producte exterior:

$$\alpha_{i\dots j} = \alpha_{[i\dots j]} \quad C_p^n = \frac{n!}{p!(n-p)!} \quad \tilde{\omega} \wedge \tilde{\sigma} = \tilde{\omega} \otimes \tilde{\sigma} - \tilde{\sigma} \otimes \tilde{\omega}$$

En una base:

$$\tilde{\alpha} = \frac{1}{p!} \alpha_{i\dots j} \tilde{\omega}^i \wedge \dots \wedge \tilde{\omega}^j$$

$$(\tilde{p} \wedge \tilde{q}) = \frac{1}{(p+q)!} (\tilde{p} \wedge \tilde{q})_{i\dots i} \tilde{\omega}^i \wedge \dots \wedge \tilde{\omega}^l = \frac{1}{p!q!} p_{[i\dots j} q_{k\dots l]} \tilde{\omega}^i \wedge \dots \wedge \tilde{\omega}^l$$

Producte interior $i(x) : \Lambda^p \rightarrow \Lambda^{p-1}$

$$\tilde{\alpha}(x) = \frac{1}{(p-1)!} \alpha_{ij\dots l} x^i \tilde{\omega}^j \wedge \dots \wedge \tilde{\omega}^l$$

Dual de Hodge $* : \Lambda^m \rightarrow \Lambda_{n-m}$

$$(*T)_{j\dots l} = \frac{1}{m!} \omega_{i\dots kj\dots l} T^{i\dots k} \quad (*B)^{j\dots l} = \frac{1}{m!} \omega^{i\dots kj\dots l} B_{j\dots k}$$

n-formes i símbol de Levi Civita

$$\omega_{1\dots n} \omega^{1\dots n} = 1 \quad \omega_{i\dots j} \omega^{i\dots j} = n! \quad \omega_{i\dots j} = f \epsilon_{i\dots j} \quad \omega^{i\dots j} = \frac{1}{f} \epsilon^{i\dots j}$$

$$\epsilon^{ijk} \epsilon_{imn} = \delta_m^j \delta_n^k - \delta_n^j \delta_m^k$$

$$\epsilon^{a_1 \dots a_j a_{j+1} \dots a_n} \epsilon_{a_1 \dots a_j b_{j+1} \dots b_n} = (n-j)! j! \delta_{b_{j+1}}^{[a_{j+1}} \dots \delta_{b_n}^{a_n]}$$

Determinant i canvi de base:

$$\det(A) = \epsilon_{ij\dots k} A^{1i} A^{2j} \dots A^{nk} = \frac{1}{n!} \epsilon_{ab\dots c} \epsilon_{ij\dots l} A^{ai} A^{bj} \dots A^{nk}$$

$$f' = f \det(\Lambda)$$

Forma volum mètric:

$$\mathbf{g} = \pm \tilde{\omega}^{1'} \otimes \tilde{\omega}^{1'} \pm \dots \pm \tilde{\omega}^{n'} \otimes \tilde{\omega}^{n'}$$

$$\tilde{\omega} = \tilde{\omega}^{1'} \wedge \dots \wedge \tilde{\omega}^{n'} = \sqrt{|\det(\mathbf{g})|} \tilde{d}x^1 \wedge \dots \wedge \tilde{d}x^n$$

Derivada exterior

$$\tilde{d}\tilde{\alpha} = \frac{1}{p!} \partial_l \alpha_{i\dots j} \tilde{d}x^l \wedge \tilde{d}x^i \wedge \dots \wedge \tilde{d}x^j$$

$$\tilde{d}(\tilde{\alpha} + \tilde{\beta}) = \tilde{d}\tilde{\alpha} + \tilde{d}\tilde{\beta} \quad \tilde{d}(\tilde{\alpha} \wedge \tilde{\beta}) = (\tilde{d}\tilde{\alpha}) \wedge \tilde{\beta} + (-1)^p \tilde{\alpha} \wedge (\tilde{d}\tilde{\beta})$$

$$\tilde{d}(\tilde{d}\tilde{\alpha}) = 0 \quad \tilde{d}(f) = \tilde{d}f = \text{grad} f \quad \tilde{d}(f\tilde{d}g) = \tilde{d}f \wedge \tilde{d}g$$

Aplicacions:

$$\mathbb{E}^3 \rightarrow *(\tilde{u} \wedge \tilde{v}) \equiv \vec{u} \times \vec{v}$$

$$*\tilde{d}\tilde{\alpha} \equiv \vec{\nabla} \times \vec{a} \quad \tilde{d}^* \vec{a} = (\text{div} \vec{a}) \tilde{\omega} = (\text{div} \vec{a}) \tilde{d}x^1 \wedge \tilde{d}x^2 \wedge \tilde{d}x^3$$

Integració

$$\int_{\Omega} \tilde{\alpha} = \int_{\mathcal{U} \subset \mathbb{R}^n} \tilde{\alpha}(\vec{e}_i, \dots, \vec{e}_j) \frac{\partial x^i}{\partial \lambda^a} \dots \frac{\partial x^j}{\partial \lambda^b} \tilde{d}\lambda^a \dots \tilde{d}\lambda^b$$

Teorema de Stokes i 0-formes:

$$\int_{\Omega} \tilde{d}\tilde{\alpha} = \int_{\partial\Omega} \tilde{\alpha} \quad \int_{\Omega} *f = \int_{\Omega} f \sqrt{|\det(g)|} \tilde{d}x^1 \wedge \dots \wedge \tilde{d}x^n$$

Teorema de Gauss:

$$\int_{\partial\Omega} *\vec{v} = \int_{\Omega} \tilde{d}*\vec{v} \quad \int_{\partial\Omega} v^i n_i \tilde{d}\lambda^1 \wedge \dots \wedge \tilde{d}\lambda^{n-1} = \int_{\Omega} (\text{div}_{\tilde{\omega}} \vec{v}) \tilde{\omega}$$

Connexió i derivada covariant

$$\nabla_{\vec{x}}(\vec{y} \otimes \vec{z}) = (\nabla_{\vec{x}} \vec{y}) \otimes \vec{z} + \vec{y} \otimes (\nabla_{\vec{x}} \vec{z})$$

$$\nabla_{\vec{x}}(\tilde{\sigma}(\vec{y})) = (\nabla_{\vec{x}} \tilde{\sigma})(\vec{y}) + \tilde{\sigma}(\nabla_{\vec{x}} \vec{y})$$

$$\nabla_{\vec{x}}(f\vec{z}) = (\nabla_{\vec{x}} f)\vec{z} + f(\nabla_{\vec{x}} \vec{z})$$

$$\nabla_{\vec{x}}(t) = \vec{x}(t)$$

$$\nabla_{f\vec{x} + g\vec{y}} \vec{z} = f \nabla_{\vec{x}} \vec{z} + g \nabla_{\vec{y}} \vec{z}$$

$$\nabla_{\vec{e}_j} \vec{e}_k = \Gamma_{kj}^i \vec{e}_i \quad (\nabla \vec{y})(\vec{\sigma}, \vec{x}) = \nabla_j y^i \sigma_i x^j \rightarrow x^j \nabla_j y^i = (\nabla_{\vec{x}} \vec{y})^i$$

$$\nabla_j y^i = \partial_j(y^i) + \Gamma_{kj}^i y^k \quad \nabla_j \sigma_i = \partial_j \sigma_i - \Gamma_{ij}^k \sigma_k$$

$$\nabla_i T_{l\dots m}^{j\dots k} = \partial_i T_{l\dots m}^{j\dots k} + \Gamma_{si}^j T_{l\dots m}^{s\dots k} + \dots + \Gamma_{si}^k T_{l\dots m}^{j\dots s} - \Gamma_{li}^s T_{s\dots m}^{j\dots k} - \dots - \Gamma_{mi}^s T_{l\dots s}^{j\dots k}$$

Connexió simètrica:

$$\begin{aligned}\Gamma_{kl}^i &= \Gamma_{lk}^i \\ \nabla_{\vec{y}}\vec{x} - \nabla_{\vec{x}}\vec{y} &= [\vec{x}, \vec{y}] = \mathcal{L}_{\vec{x}}\vec{y} \\ \mathcal{L}_{\vec{x}}\vec{\sigma} &= x^k \nabla_k \sigma_i + \sigma_k \nabla_i x^k\end{aligned}$$

Connexió mètrica:

$$\begin{aligned}\nabla \mathbf{g} &= 0 \quad \nabla_\alpha g_{\mu\nu} = 0 \\ \Gamma_{ji}^l &= \frac{1}{2} g^{lm} (\partial_j g_{mi} + \partial_i g_{mj} - \partial_m g_{ij})\end{aligned}$$

Transport paral·lel:

$$\begin{aligned}\nabla_{\vec{v}}\vec{u} &= 0 \rightarrow v^k \partial_k u^i + \Gamma_{lk}^i v^l u^k = 0 \\ \frac{du^i}{d\lambda} + \Gamma_{lk}^i \frac{dx^l}{d\lambda} u^k &= 0\end{aligned}$$

Geodèsiques

$$\nabla_{\vec{v}}\vec{v} = 0 \rightarrow \frac{d^2 x^k}{d\lambda^2} + \Gamma_{li}^k \frac{dx^l}{d\lambda} \frac{dx^i}{d\lambda} = 0$$

Curvatura de la connexió

Tensor de Riemann: $\mathbb{R}(\vec{x}, \vec{y}) \equiv [\nabla_{\vec{x}}, \nabla_{\vec{y}}] - \nabla_{[\vec{x}, \vec{y}]}$

$$\begin{aligned}[\nabla_{\vec{e}_i}, \nabla_{\vec{e}_j}]\vec{e}_k - \nabla_{[\vec{e}_i, \vec{e}_j]}\vec{e}_k &= R_{kij}^l \vec{e}_l \\ R_{kij}^l &= \partial_i \Gamma_{kj}^l - \partial_j \Gamma_{ki}^l + \Gamma_{kj}^m \Gamma_{mi}^l - \Gamma_{ki}^m \Gamma_{mj}^l\end{aligned}$$

Amb $\frac{n^2(n^2-1)}{12}$ components independents.

$$\begin{aligned}R_{k(ij)}^l &= 0 \quad R_{[kij]}^l = 0 \quad R_{k[ij;m]} = 0 \\ R_{klmn} &= g_{ki} R_{lmn}^i\end{aligned}$$

Tensor de Ricci i escalar de Ricci:

$$R_{ik} = R_{imk}^m \quad R = g^{ik} R_{ik} \quad \nabla^\mu R_{\rho\mu} = -\frac{1}{2} \nabla_\rho R$$

Tensor d'Einstein:

$$G_{ij} \equiv R_{ij} - \frac{1}{2} g_{ij} R \quad G = -R \quad \nabla_i G^{ij} = 0$$

Divergència (respecte connexió Levi-Civita):

$$\Gamma_{\mu\lambda}^\mu = \frac{1}{\sqrt{|\mathbf{g}|}} \partial_\lambda \sqrt{|\mathbf{g}|} \quad \nabla_\mu v^\mu = \partial_\mu v^\mu + \Gamma_{\mu\lambda}^\mu v^\lambda = \frac{1}{\sqrt{|\mathbf{g}|}} \partial_\mu (\sqrt{|\mathbf{g}|} v^\mu)$$

II. RELATIVITAT GENERAL

$$R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = 8\pi T_{\mu\nu}$$

Simetria Esfèrica i Forats Negres

Estàtic: killing temps + $g_{0i} = 0$

$$ds^2 = -e^{2\phi(t,r)} dt^2 + e^{2\Lambda(t,r)} dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

$$l_{12} = \int_{r_1}^{r_2} \sqrt{e^{2\Lambda}} dr \quad \frac{\omega_1}{\omega_2} = e^{\phi(r_2) - \phi(r_1)}$$

Mètrica de Schwarzschild:

$$ds^2 = -\left(1 - \frac{2M}{r}\right) dt^2 + \frac{dr^2}{1 - \frac{2M}{r}} + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

Dinàmica:

$$g_{\alpha\beta} u^\alpha u^\beta = -1 \quad g_{\alpha\beta} k^\alpha k^\beta = 0 \quad -k_\alpha u^\alpha = \omega$$

Si ξ^α és Killing i v^μ geodèsica, $\xi^\alpha v_\alpha = g_{\alpha\beta} \xi^\alpha v^\beta = \text{const.}$

$$u_0 \equiv -\hat{E} \quad k_0 \equiv -E \quad u_\phi \equiv \hat{L} \quad k_\phi \equiv L$$

Trajectòries:

$$\left(\frac{dr}{d\tau}\right)^2 = \hat{E}^2 - \left(1 - \frac{2M}{r}\right) \left(1 + \frac{\hat{L}^2}{r^2}\right) \quad \left(\frac{dr}{d\lambda}\right)^2 = E^2 - \left(1 - \frac{2M}{r}\right) \frac{L^2}{r^2}$$

Mínim estable:

$$\hat{L}^2 = \frac{Mr}{1 - \frac{3M}{r}} \quad \hat{E}^2 = \frac{\left(1 - \frac{2M}{r}\right)^2}{1 - \frac{3M}{r}}$$

$$r = \frac{\hat{L}^2}{2M} \left(1 \pm \sqrt{1 - \frac{12M^2}{\hat{L}^2}}\right)$$

Coordenades de Kruskal-Szekeres:

$$X = \left(\frac{r}{2M} - 1\right)^{\frac{1}{2}} e^{r/4M} \cosh\left(\frac{t}{4M}\right)$$

$$T = \left(\frac{r}{2M} - 1\right)^{\frac{1}{2}} e^{r/4M} \sinh\left(\frac{t}{4M}\right)$$

$$ds^2 = \frac{32M^3 e^{-r/2M}}{r} (-dT^2 + dX^2) + r^2 d\Omega^2$$

Teoria Linealitzada i Ones Gravitacionals

$$g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu} \quad |h_{\mu\nu}| \ll 1 \quad \bar{h}_{\mu\nu} = h_{\mu\nu} - \frac{1}{2} \eta_{\mu\nu} h^\alpha_\alpha$$

$$h_{\mu\nu} \rightarrow h'_{\mu\nu} = h_{\mu\nu} - 2\partial_{(\mu} \xi_{\nu)}$$

Gauge de Lorentz: $\partial^\mu \bar{h}_{\mu\nu} = 0 \quad \square^2 \xi_\nu = \partial^\mu h_{\mu\nu}$

Equacions linealitzades + gauge: $\partial_\alpha \partial^\alpha \bar{h}_{\mu\nu} = -2\kappa T_{\mu\nu}$

Gauge TT: $h_{\alpha 0} = 0, h^\alpha_\alpha = 0, \partial^i h_{ik} = 0$

$$\bar{h}_{\mu\nu} \rightarrow \bar{h}'_{\mu\nu} = \bar{h}_{\mu\nu} - 2\partial_{(\mu} \xi_{\nu)} + \partial^\alpha \xi_\alpha$$

Ones planes:

$$\bar{h}_{\mu\nu} = \text{Re} [A_{\mu\nu} \exp(il_\alpha x^\alpha)] \quad l^\alpha = (\omega, \vec{k})$$

$$l_\alpha l^\alpha = \bar{h}_{\mu\nu} l^\nu = R_{\alpha\beta\mu\nu} l^\nu = l^\alpha \nabla_\alpha l^\mu = \nabla_\alpha l^\mu = 0 \quad il_\nu = \partial_\nu$$

Potència:

$$P = \frac{dE}{dt} = \frac{G}{5c^5} \langle \ddot{I}_{ij} \ddot{I}_{ij} \rangle \quad \ddot{I}_{ij} = D_{ij} - \frac{1}{3} \delta_{ij} D_k^k$$

$$D^{ij} = \int T^{00}(x) x^i x^j d^3 x' = \sum_\alpha m_\alpha x_\alpha^i x_\alpha^j$$

Límit Newtonià:

$$\text{Schw: } ds^2 = -(1 - 2\phi) dt^2 + dx^2 + dy^2 + dz^2 \quad \phi = \frac{M}{R+x}$$

$$p \ll \rho \quad dt = d\tau \quad |\partial_0| \ll |\partial_i|$$

$$u^\mu = (1, v^i) \quad |v^i| \ll 1$$